

No class Monday 9/5 for Labor-day holiday.

For Wednesday 9/7 discussion problems

2.6 319-330 sketch the surface given by the equation shown.

2.7 problems on syllabus.

2.4

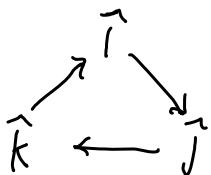
(184) Calculate $\vec{u} \times \vec{v}$ where $\vec{u} = \langle 3, 2, -1 \rangle = 3\hat{i} + 2\hat{j} - \hat{k}$
 $\vec{v} = \langle 1, 1, 0 \rangle = \hat{i} + \hat{j}$

$$\vec{u} \times \vec{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 3 & 2 & -1 \\ 1 & 1 & 0 \end{vmatrix} = \left\langle \begin{vmatrix} 2 & -1 \\ 1 & 0 \end{vmatrix}, - \begin{vmatrix} 3 & -1 \\ 1 & 0 \end{vmatrix}, \begin{vmatrix} 3 & 2 \\ 1 & 1 \end{vmatrix} \right\rangle$$

$$= \langle 0 - (-1), - (0 - (-1)), 3 - 2 \rangle$$

$$= \langle 1, -1, 1 \rangle$$

another method



$$\begin{aligned}\hat{i} \times \hat{i} &= 0 \\ \hat{j} \times \hat{j} &= 0 \\ \hat{k} \times \hat{k} &= 0\end{aligned}$$

$$(3\hat{i} + 2\hat{j} - \hat{k}) \times (\hat{i} + \hat{j}) = \leftarrow \text{distribution}$$

$$\begin{aligned}3\hat{i} \times \hat{i} + 3\hat{i} \times \hat{j} + 2\hat{j} \times \hat{i} + 2\hat{j} \times \hat{j} - \hat{k} \times \hat{i} - \hat{k} \times \hat{j} &= 3\hat{k} - 2\hat{k} - \hat{j} + \hat{i} = \hat{i} - \hat{j} + \hat{k} \\ &= \langle 1, -1, 1 \rangle\end{aligned}$$

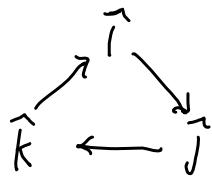
4-dimensional unit vectors

$$1 = \langle 1 \ 0 \ 0 \ 0 \rangle$$

$$\hat{i} = \langle 0 \ 1 \ 0 \ 0 \rangle$$

$$\hat{j} = \langle 0 \ 0 \ 1 \ 0 \rangle$$

$$\hat{k} = \langle 0 \ 0 \ 0 \ 1 \rangle$$



$$\hat{i} \times \hat{i} = -1$$

$$\hat{j} \times \hat{j} = -1$$

$$\hat{k} \times \hat{k} = -1$$

$$\hat{i} \times \hat{j} = \hat{j} \times \hat{i} = \hat{i}$$

etc...

$$\vec{u} = \langle -1, 0, e^t \rangle \quad \vec{v} = \langle 1, e^{-t}, 0 \rangle$$

find \vec{w} orthogonal to both \vec{u} and \vec{v} .

Of course we can choose $\vec{w} = \vec{u} \times \vec{v}$ or $t\vec{c}(\vec{u} \times \vec{v})$ for any scalar $t\vec{c}$.

$$\vec{w} = \vec{u} \times \vec{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -1 & 0 & e^t \\ 1 & e^{-t} & 0 \end{vmatrix} = \langle -1, e^t, -e^{-t} \rangle$$

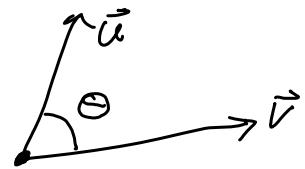
check $\langle -1, e^t, -e^{-t} \rangle \cdot \langle -1, 0, e^t \rangle = 1 + 0 - 1 = 0$

$$\langle -1, e^t, -e^{-t} \rangle \cdot \langle 1, e^{-t}, 0 \rangle = -1 + 1 + 0 = 0$$

✓

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$$\vec{u} = \langle -1, 3, 1 \rangle \quad \vec{v} = \langle 1, -2, 0 \rangle$$



$$\vec{u} \times \vec{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -1 & 3 & 1 \\ 1 & -2 & 0 \end{vmatrix} = \langle 2, 1, -1 \rangle$$

a property cross products

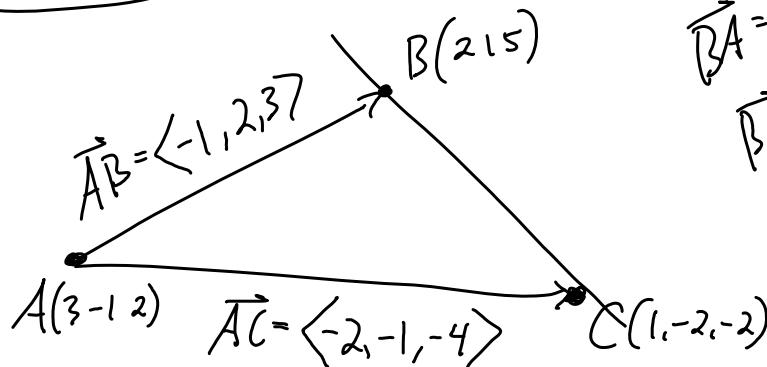
$$|\vec{u} \times \vec{v}| = |\vec{u}| |\vec{v}| \sin(\theta)$$

$$\sqrt{6} = \sqrt{11} \sqrt{5} \sin(\theta)$$

$$\sqrt{\frac{6}{55}} = \sin(\theta)$$

$$\text{Arcsin}\left(\sqrt{\frac{6}{55}}\right) = \theta$$

$$19.29^\circ \approx 0$$



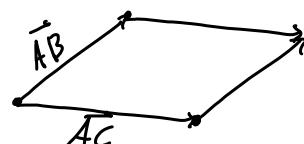
$$\begin{aligned} \vec{BA} &= \langle 1, -2, -3 \rangle \\ \vec{BC} &= \langle -1, 3, -7 \rangle \end{aligned}$$

$$\frac{|\vec{BA} \times \vec{BC}|}{|\vec{BC}|} =$$

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & -2 & -3 \\ -1 & 3 & -7 \end{vmatrix} = \langle 5, 10, -5 \rangle$$

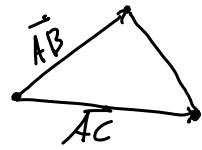
$$\vec{AB} \times \vec{AC} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -1 & 2 & 3 \\ -2 & -1 & -4 \end{vmatrix} = \langle -5, -10, 5 \rangle$$

$$|\vec{AB} \times \vec{AC}| = 5 \langle 1, 2, 1 \rangle = 5\sqrt{6}$$



② Area of parallelogram defined by \vec{AB} and \vec{AC} = $5\sqrt{6}$

① Area of triangle defined by \vec{AB} and \vec{AC} = $\frac{5}{2}\sqrt{6}$

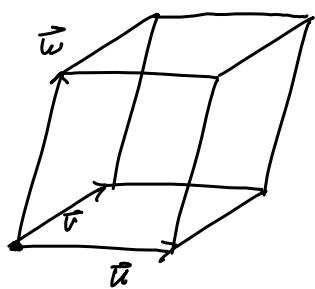


② $|AB| \sin(\theta) = \frac{|AB| |AC| \sin(\theta)}{|AC|} = \frac{|\vec{AB} \times \vec{AC}|}{|\vec{AC}|} = \frac{5\sqrt{6}}{\sqrt{21}} = 5\sqrt{\frac{6}{21}}$

Another solution

$\text{Orth}_{AC}(\vec{AB}) = \vec{AB} - \text{Proj}_{AC}(\vec{AB})$ distance we want is $|\text{Orth}_{AC}(\vec{AB})|$

② 14



Volume of this "parallelepiped" is
 $|u \cdot (v \times w)|$ which is the absolute value of the 3×3 determinant

$$\begin{vmatrix} \vec{u} \\ \vec{v} \\ \vec{w} \end{vmatrix}$$

In This example

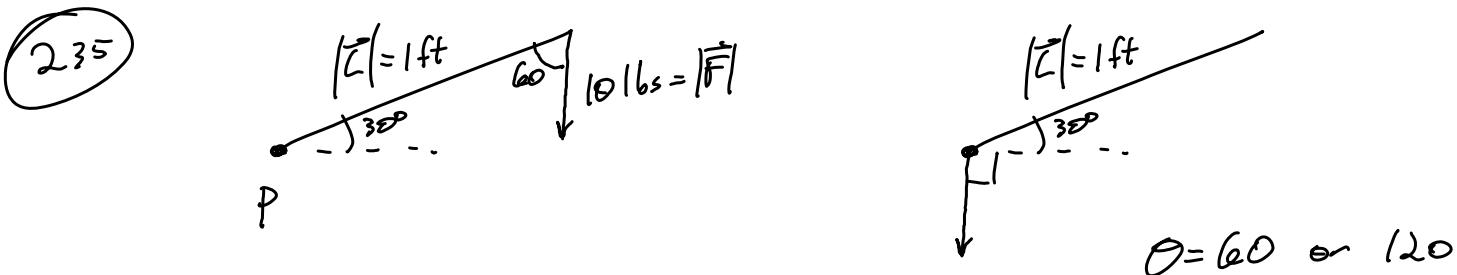
$$\vec{u} = \langle -3 \ 5 \ -1 \rangle$$

$$\vec{v} = \langle 0 \ 2 \ -2 \rangle$$

$$\vec{w} = \langle 3 \ 1 \ 1 \rangle$$

$$\text{So volume} = \begin{vmatrix} -3 & 5 & -1 \\ 0 & 2 & -2 \\ 3 & 1 & 1 \end{vmatrix} = \begin{vmatrix} -3 & 2-3 \\ 1 & 1 \end{vmatrix} - \begin{vmatrix} 0 & -2 \\ 3 & 1 \end{vmatrix} + (-1) \begin{vmatrix} 0 & 3 \\ 3 & 1 \end{vmatrix}$$
$$= \begin{vmatrix} -3(1) - 5(6) - (-6) \end{vmatrix}$$
$$= \begin{vmatrix} -12 - 30 + 6 \end{vmatrix} = \boxed{36}$$

(221) unit



$$\text{Torque} = |\vec{L}|(\vec{F} \sin \theta)$$

$$= 1 \cdot 10 \sin(60^\circ) = \boxed{5\sqrt{3} \text{ ft-lbs}}$$

2.5

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$$P(-3, 5, 9)$$

$$Q(4, -7, 2)$$

$$\overrightarrow{PQ} = \langle 7, -12, -7 \rangle$$

vector equation $\langle x, y, z \rangle = \langle -3, 5, 9 \rangle + t \langle 7, -12, -7 \rangle$

parametric equations

$$\begin{cases} X = -3 + 7t \\ Y = 5 - 12t \\ Z = 9 - 7t \end{cases}$$

Line segment from P to Q

$$\begin{cases} X = -3 + 7t \\ Y = 5 - 12t \text{ with } 0 \leq t \leq 1 \\ Z = 9 - 7t \end{cases}$$

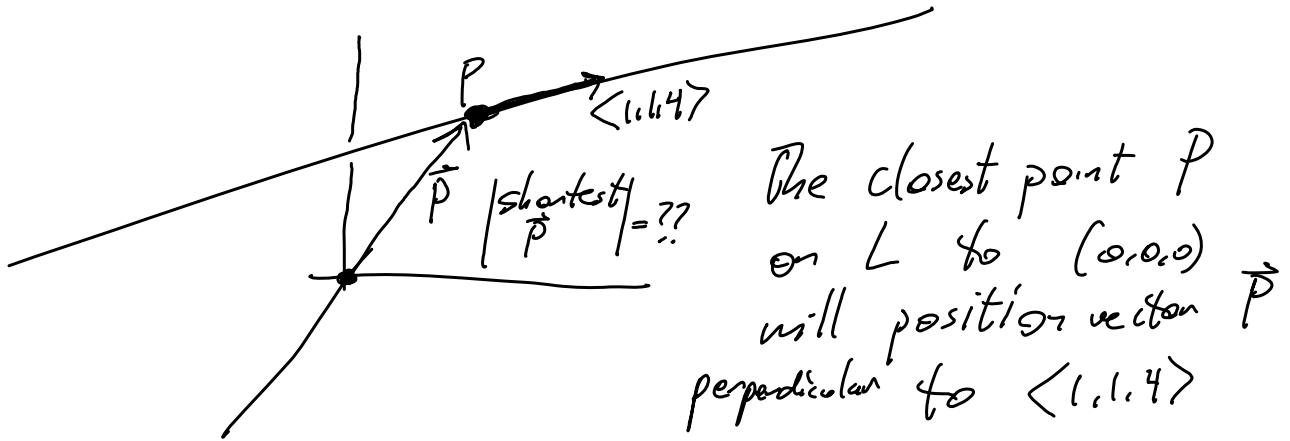
Symmetric equations

$$\frac{x+3}{7} = \frac{y-5}{-12} = \frac{z-9}{-7}$$

251

$$\begin{cases} X = 1 + t \\ Y = 3 + t \\ Z = 5 + 4t \end{cases}$$

a point on the line $(1, 3, 5)$
 slope vector $\langle 1, 1, 4 \rangle$



The closest point P
 on L to $(0, 0, 0)$
 will position vector \vec{P}
 perpendicular to $\langle 1, 1, 4 \rangle$

$\vec{P} = \langle x, y, z \rangle$ and $\langle x, y, z \rangle \cdot \langle 1, 1, 4 \rangle = 0$
 and $\langle x, y, z \rangle$ is on L .

Since $\langle x_1, y_1, z_1 \rangle$ is on L $\langle x_1, y_1, z_1 \rangle = \langle 1+t, 3+t, 5+4t \rangle$ and

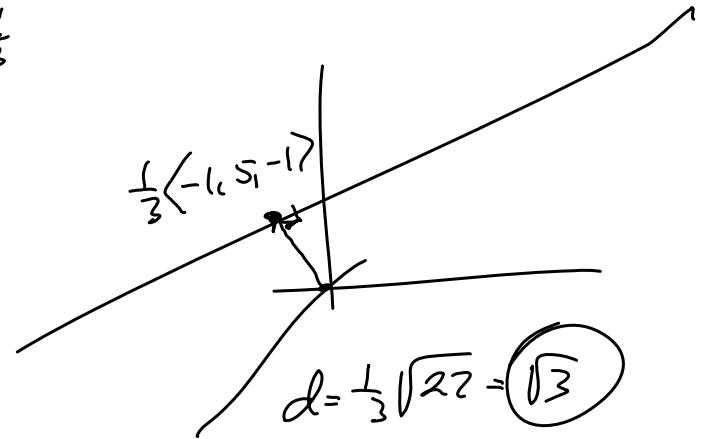
$$\langle 1+t, 3+t, 5+4t \rangle \cdot \langle 1, 1, 4 \rangle = 0$$

$$(1+t+3+t+4(5+4t)) = 0$$

$$24 + 18t = 0$$

$$t = \frac{-24}{18} = -\frac{4}{3}$$

$$\langle x_1, y_1, z_1 \rangle = \left\langle -\frac{1}{3}, \frac{5}{3}, -\frac{1}{3} \right\rangle$$



(255)

$$\begin{cases} x = 1+t \\ y = t \\ z = 2+t \end{cases} \quad L_1$$

$$\text{slope} = \langle 1, 1, 1 \rangle$$

2 points on L_1

$$(1, 0, 2)$$

$$(2, 1, 3)$$

$$\boxed{x-3 = y-1 = z-3} \quad L_2$$

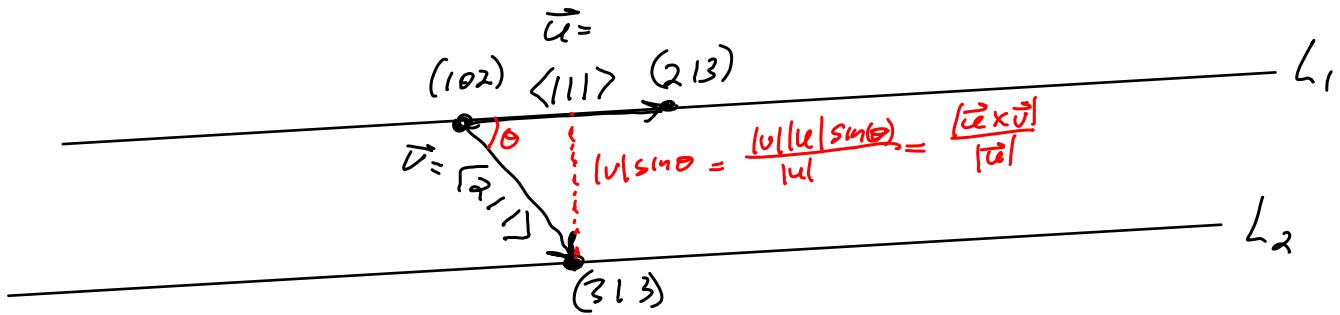
$$\begin{cases} x = 3+t \\ y = 1+t \\ z = 3+t \end{cases}$$

$$\text{slope} = \langle 1, 1, 1 \rangle$$

a point on L_2

$$(3, 1, 3)$$

lines are parallel



$$\vec{u} \times \vec{v} = \begin{vmatrix} i & j & k \\ 1 & 1 & 1 \\ 2 & 1 & 1 \end{vmatrix} = \langle 0, 1, -1 \rangle \quad |\vec{u} \times \vec{v}| = \sqrt{2}$$

$$|\vec{u}| = \sqrt{3}$$

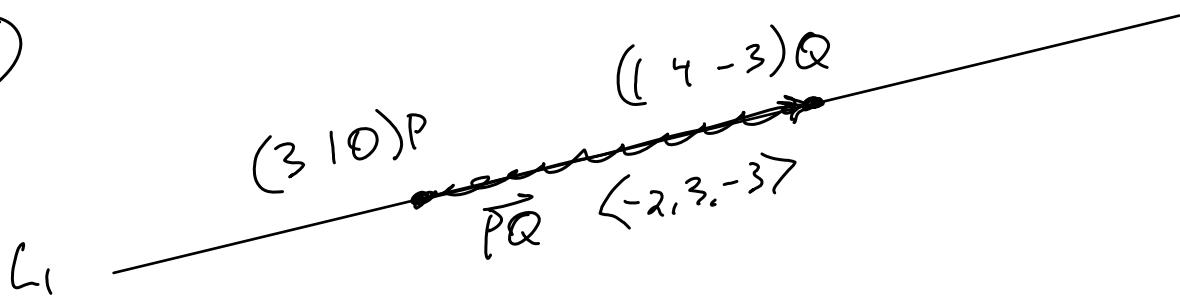
$$\text{distance}_{L_1 \text{ to } L_2} = \frac{|\vec{u} \times \vec{v}|}{|\vec{v}|} = \boxed{\sqrt{\frac{2}{3}}}$$

(256)

slope vectors $\langle 0, 0, 1 \rangle$ and $\langle 0, 0, -3 \rangle$

so they are parallel. Find the distance on your own.

(257)



L_2 has slope $\langle 3, 8, 6 \rangle$

$$\text{Because } \langle -2, 3, -3 \rangle \cdot \langle 3, 8, 6 \rangle = -6 + 24 - 18 = 0$$

This means the lines w/ these slopes are perpendicular.

(261)

$$L_1: x = y - 1 = -z$$

$$L_2: x - 2 = -y = \frac{z}{2}$$

$$x = t$$

$$x = 2 + t$$

$$y = 1 + t$$

$$y = -t$$

$$z = -t$$

$$z = 2t$$

$$\text{slope} = \langle 1, 1, -1 \rangle$$

$$\text{slope} = \langle 1, -1, 2 \rangle$$

L_1 and L_2
are skew
or intersecting.

If L_1 and L_2 intersect, then there is a solution to

$$\begin{aligned} t = 2+s &\longrightarrow t-s = 2 \\ 1+t = -s &\longrightarrow t = -2-s \\ -t = 2s & \quad -2s-s = 2 \\ & \quad -3s = 2 \\ & \boxed{s = -\frac{2}{3}} \\ & \boxed{t = \frac{4}{3}} \end{aligned}$$

(264)

4

$$3x = y+1 = 2z$$

$$\begin{cases} x = \frac{1}{3}t \\ y = -1+t \\ z = \frac{1}{2}t \end{cases}$$

$$\text{slope} = \left\langle \frac{1}{3}, 1, \frac{1}{2} \right\rangle$$

$$\begin{array}{|c|} \hline L_2 \\ \hline \begin{array}{l} 6t+2t=x \\ 17+6t=y \\ 9t+3t=z \end{array} \\ \hline \end{array}$$

$$\text{slope} = \langle 2, 6, 3 \rangle$$

parallel or equal.

L_1 contains the point $(0, -1, 0)$. Thus $L_2 = L_1$ if and only if

L_2 also contains $(0, -1, 0)$.

$$x = 6t+2t=0$$

$$\begin{array}{|c|} \hline t = -3 \\ \hline \end{array}$$

$$\text{using } t = -3 \quad (x, y, z) = (0, -1, 0)$$

$$1+t = -s$$

$$1 + \frac{4}{3} \neq -\frac{2}{3} \text{ so } L_1 \text{ and } L_2$$

are skew
because there
is no intersection
point.